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Notice of Allowability	Application No.	Applicant(s)	
	10/733,318	HIRAI ET AL.	
	Examiner	Art Unit	
	Sean P. Shechtman	2125	
The MAILING DATE of this communication appearable communication appearable claims being allowable, PROSECUTION ON THE MERITS IS (herewith (or previously mailed), a Notice of Allowance (PTOL-85) NOTICE OF ALLOWABILITY IS NOT A GRANT OF PATENT RIGOR (The Office or upon petition by the applicant. See 37 CFR 1.313	OR REMAINS) CLOSED in this ap or other appropriate communication GHTS. This application is subject to	plication. If not include will be mailed in due	ed course. THIS
1. This communication is responsive to <u>07 April 2005</u> .			
2. The allowed claim(s) is/are 1-5.			
3. \boxtimes The drawings filed on <u>07 April 2005</u> are accepted by the Ex	aminer.		
4. Acknowledgment is made of a claim for foreign priority und a) All b) Some* c) None of the: 1. Certified copies of the priority documents have 2. Certified copies of the priority documents have 3. Copies of the certified copies of the priority doc International Bureau (PCT Rule 17.2(a)). * Certified copies not received: Applicant has THREE MONTHS FROM THE "MAILING DATE" of noted below. Failure to timely comply will result in ABANDONMETHIS THREE-MONTH PERIOD IS NOT EXTENDABLE. 5. A SUBSTITUTE OATH OR DECLARATION must be submit INFORMAL PATENT APPLICATION (PTO-152) which give 6. CORRECTED DRAWINGS (as "replacement sheets") must (a) including changes required by the Notice of Draftsperson 1) hereto or 2) to Paper No./Mail Date (b) including changes required by the attached Examiner's Paper No./Mail Date Identifying indicia such as the application number (see 37 CFR 1.8 each sheet. Replacement sheet(s) should be labeled as such in the 1. DEPOSIT OF and/or INFORMATION about the depose attached Examiner's comment regarding REQUIREMENT F	been received. been received in Application No cuments have been received in this of this communication to file a reply ENT of this application. Itted. Note the attached EXAMINER is reason(s) why the oath or declara to be submitted. on's Patent Drawing Review (PTO- Amendment / Comment or in the Comment or in the Comment of the drawing replaced in the declaration of the drawing replaced in the Comment of the drawing replaced in the Comment of the	national stage applical complying with the recomplying attached. Office action of the one of the one of the one of the recomplying in the front (not the od).	quirements IOTICE OF
 Attachment(s) 1. ☐ Notice of References Cited (PTO-892) 2. ☐ Notice of Draftperson's Patent Drawing Review (PTO-948) 3. ☒ Information Disclosure Statements (PTO-1449 or PTO/SB/08 Paper No./Mail Date 12/12/03 4. ☐ Examiner's Comment Regarding Requirement for Deposit of Biological Material 	5. ☐ Notice of Informal F 6. ☐ Interview Summary Paper No./Mail Da 7. ☑ Examiner's Amenda 8. ☑ Examiner's Statema 9. ☐ Other	(PTO-413), te ment/Comment	·

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DETAILED ACTION

1. Claims 1-5 are presented for examination.

EXAMINER'S AMENDMENT

An examiner's amendment to the record appears below. Should the changes and/or additions be unacceptable to applicant, an amendment may be filed as provided by 37 CFR 1.312. To ensure consideration of such an amendment, it MUST be submitted no later than the payment of the issue fee.

Authorization for this examiner's amendment was given by Melvin Kraus in an amendment filed on April 7th 2005.

The application has been amended as follows:

2. Referring to the title, -- Numerically Controlled Curved Surface Machining Unit -- has been inserted, replacing "Compensation Numerically Controlled Curved Surface Machining Unit".

Drawings

3. Objections withdrawn due to the amendment.

Specification

4. Objections withdrawn.

Allowable Subject Matter

5. Claims 1-5 are allowed.

The following is an examiner's statement of reasons for allowance:

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While Jai teaches a method and system for interpolating NURBS curves on a numerically controlled machine tool, and using a controlled step size based on the desired feed rate, and providing an approximate measure of the distance left to travel.

And, Tanaka teaches arithmetic operation for transformation between coordinate systems with respect to the points given by the following a coordinate transformation matrix indicative of angles of rotation between the coordinate systems and a vector indicative of parallel shifts between the coordinate systems.

Neither of these references taken either alone or in combination teach a numerically controlled curved-surface machining unit equipped with three linearly moving axes and, at least, one rotary axis, including a simultaneous multiple-axis control NC machine numerically controlled by a numerical control unit with a numerical control NURBS interpolation function, having all the claimed features of applicant's instant invention, specifically including: "component converting matrix*angle-addition value forming means for converting CL (cutter location) data composed of tool control point vector data and tool axis vector data, calculated along a machining direction on a workpiece coordinate system on which a curved surface is defined by a host computer into components on a normal coordinate system for operating said simultaneous multiple-axis control NC machine on the basis of the machine configuration of said simultaneous multiple-axis control NC machine" and machine coordinate converting means for converting the tool control point vectors into the machine coordinate system by using a machine coordinate transforming matrix that obtains a matrix for converting the tool control point vectors on the workpiece coordinate system into a machine coordinate system by using first angles and second angles formed on axes of normal coordinate system.

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Any comments considered necessary by applicant must be submitted no later than the payment of the issue fee and, to avoid processing delays, should preferably accompany the issue fee. Such submissions should be clearly labeled "Comments on Statement of Reasons for Allowance."

Conclusion

6. Any inquiry concerning this communication or earlier communications from the examiner should be directed to Sean P. Shechtman whose telephone number is (571) 272-3754. The examiner can normally be reached on 9:30am-6:00pm, M-F.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Leo P. Picard can be reached on (571) 272-3749. The fax phone number for the organization where this application or proceeding is assigned is 703-872-9306.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free).

L.P.P.

SPS

Sean P. Shechtman

April 15, 2005

LEO PICARD SUPERVISORY PATENT EXAMINER TECHNOLOGY CENTER 2100

IN THE CLAIMS:

Amendments to the Claims

Please cancel claims 6-8, which are subject to a restriction requirement, without prejudice or disclaimer of the subject matter thereof and without prejudice to the filing of a divisional application directed thereto.

Listing of Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

1. (original) A numerically controlled curved-surface machining unit equipped with three linearly moving axes and, at least, one rotary axis, including a simultaneous multiple-axis control NC machine numerically controlled by a numerical control unit with a numerical control NURBS interpolation function, comprising:

component converting matrix-angle-addition value forming means for converting CL (cutter location) data composed of tool control point vector data and tool axis vector data, calculated along a machining direction on a workpiece coordinate system on which a curved surface is defined by a host computer into components on a normal coordinate system for operating said simultaneous multiple-axis control NC machine on the basis of the machine configuration of said simultaneous multiple-axis control NC machine;

component converting means for converting from the workpiece coordinate system to the normal coordinate system;

second angle forming means for forming second angles of a second rotary axis on the normal coordinate system;

second angle compensating means for forming a continuous angle distribution from a distribution of the second angles;

first angle forming means for forming first angles of a first rotary axis on a coordinate system rotated by the second angles at the second rotary axis;

first angle compensating means for forming a continuous angle distribution from a distribution of the first angles;

machine coordinate transformation matrix forming means for obtaining a matrix for converting the tool control point vectors on the workpiece coordinate system into a machine coordinate system by using said first angles and said second angles;

machine coordinate converting means for converting the tool control point vectors into the machine coordinate system by using said machine coordinate transforming matrix;

means for converting data on the machine coordinate system to NC data; and means for transmitting said NC data to said numerical control unit.

- 2. (original) A numerically controlled curved-surface machining unit according to claim 1, wherein said component converting matrix angle addition value forming means reads, as said machine configuration, data relating to the first rotary axis, the second rotary axis, a tool axis and a master axis and forms a component converting matrix converting components to the normal coordinate system, axis conversion matrix and angle addition values, and said component converting means converts the tool axis vectors into normal coordinate system components by using the component converting matrix, the axis converting matrix and the angle addition values.
- (original) A numerically controlled curved-surface machining unit according to claim 1, wherein said second angle compensating means sets an identifier by detecting the condition that both vectors for obtaining angles become 0,

obtains a difference value of adjacent angles, forms another difference value using the difference value of adjacent angles in the case where any angle is not obtained by said identifier, detect, when said difference value is larger than π , a minimum value from said difference value, said difference value $+\pi$, said difference value $-\pi$, said difference value $+2\pi$, and said difference value -2π to set the minimum difference value as a new difference value, and obtains the second angle by adding the difference value to an angle of a start point.

- 4. (original) A numerically controlled curved-surface machining unit according to claim 3, wherein said first angle compensating means detects, when said difference value is larger than π , a minimum value from said difference value, said difference value $+2\pi$ and said difference value -2π to set the minimum difference value as a new difference value, and obtains the first angle by adding the difference value to the angle of start point.
- 5. (original) A numerically controlled curved-surface machining unit according to any one of claims 1 to 4, wherein said first angle forming means forms a reference direction vector of said first angle by using said second angle, and obtains the first angle the start of which is said reference vector.

Claims 6-8 (canceled)